

# Validating Mathematical Structures

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# Packed classes

Packaging Mathematical Structures [Garillot et al. 2009]

Packed classes are generic design patterns to define and combine algebraic structures, which support:

- ▶ multiple inheritance,
- ▶ maximal sharing of notations and theories, and
- ▶ automated structure inference.

# Packed classes

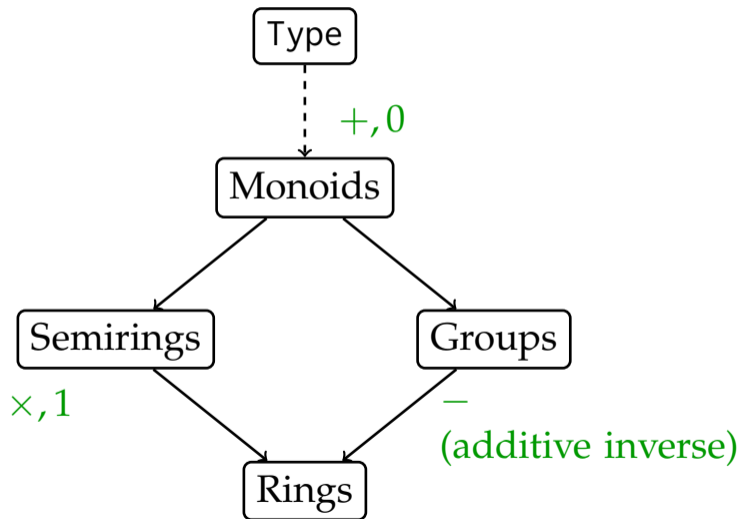
Packaging Mathematical Structures [Garillot et al. 2009]

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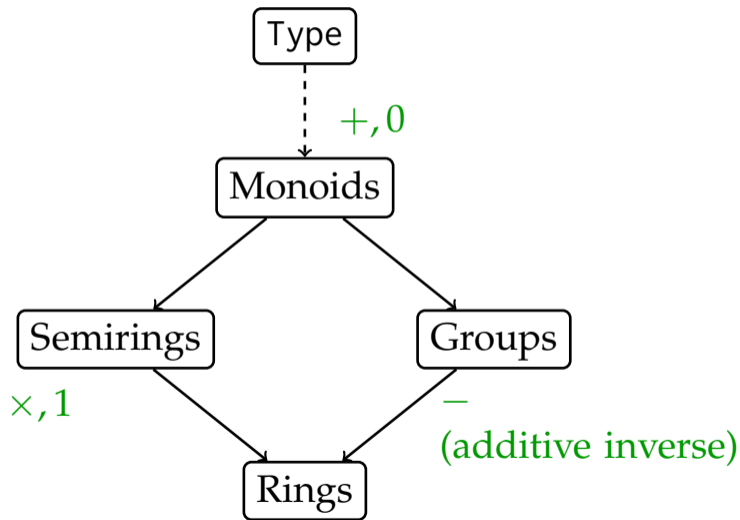
- ▶ multiple inheritance,
- ▶ maximal sharing of notations and theories, and
- ▶ **automated structure inference**:
  - ▶ requires a lot of unification hints in the form of canonical projections [Mahboubi et al. 2013] .
  - ▶ E.g., MathComp 1.9.0:  
49 structures, **547 implicit coercions**, **711 canonical projections**.



# A hierarchy with multiple inheritance



# A hierarchy with multiple inheritance



less axioms,  
more instances,  
**larger** structures



more axioms,  
less instances,  
**smaller** structures



# How to define a structure?

Module Monoid.

```
Record class_of (A : Type) := Class { (* set of operators and axioms *) }.
```

```
Structure type := Pack { sort : Type; _ : class_of sort }.
```

```
Local Definition class (cT : type) :=  
  match cT as cT' return class_of (sort cT') with Pack _ c => c end.
```

End Monoid.

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End Monoid.
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```
add   :  $\forall A : \text{Monoid.type}, \text{Monoid.sort } A \rightarrow \text{Monoid.sort } A \rightarrow \text{Monoid.sort } A$   
zero :  $\forall A : \text{Monoid.type}, \text{Monoid.sort } A$ 
```



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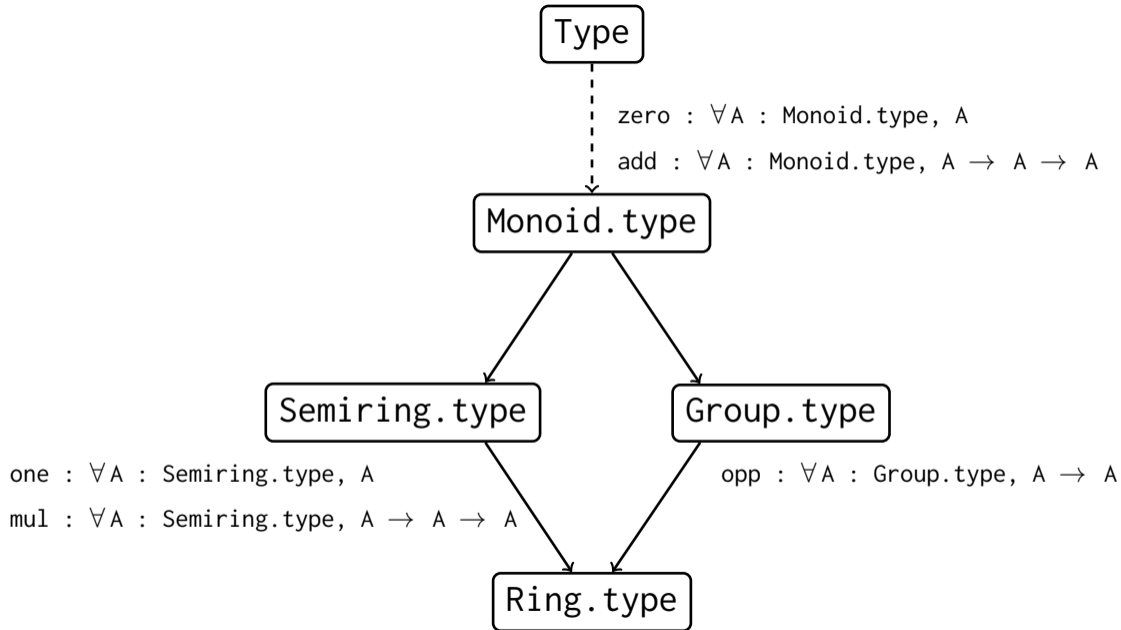
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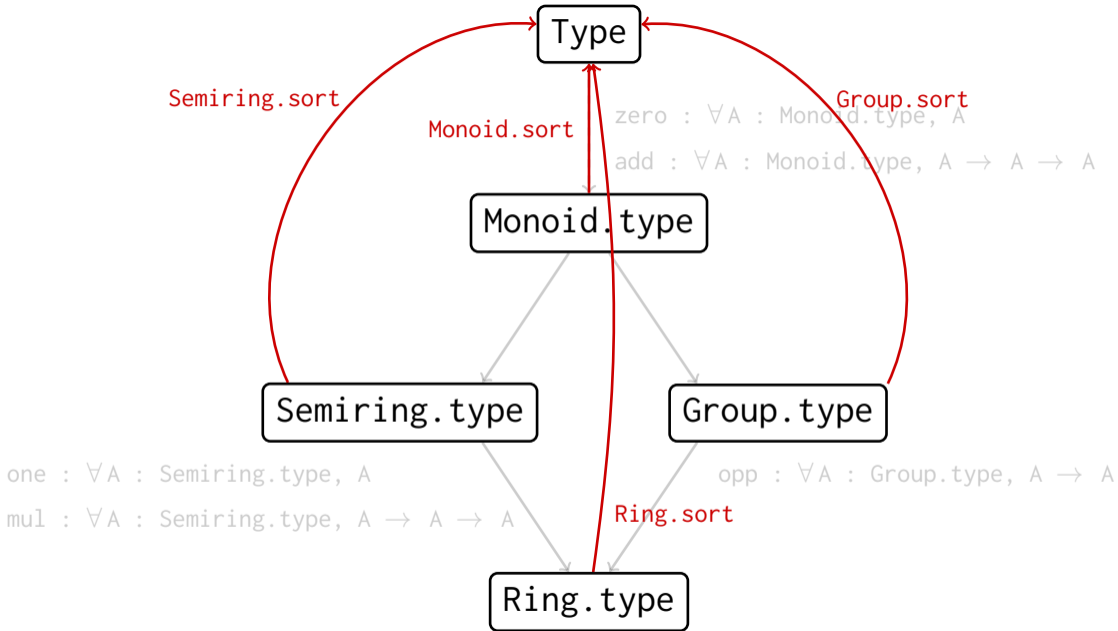
End Monoid.

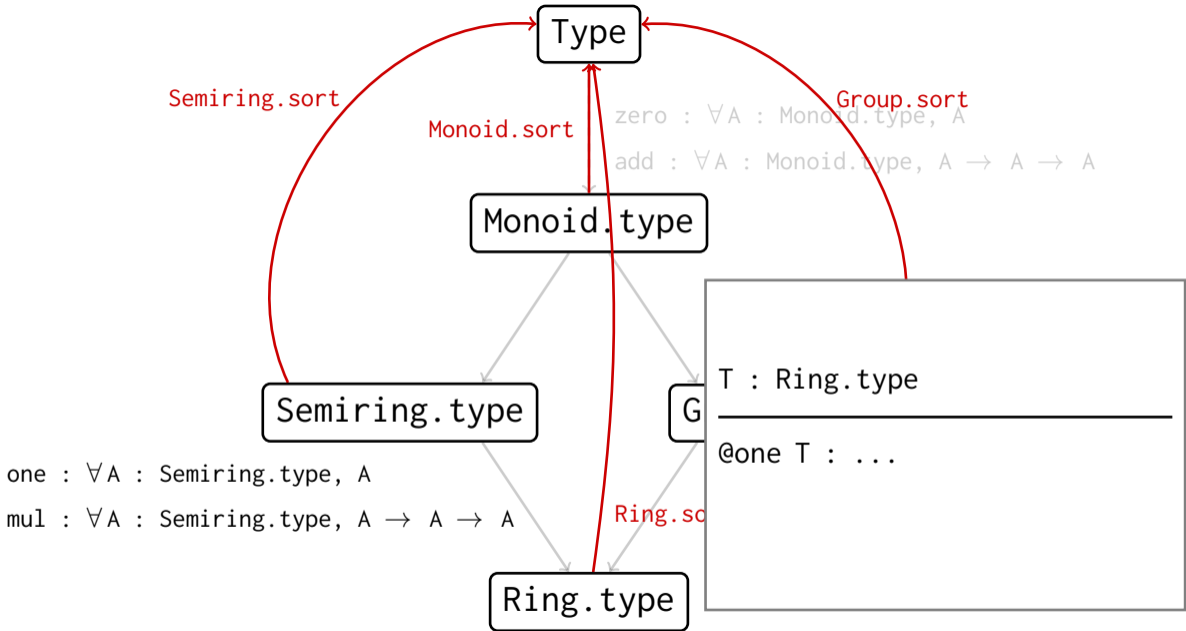
Coercion Monoid.sort : Monoid.type >-> Sortclass.

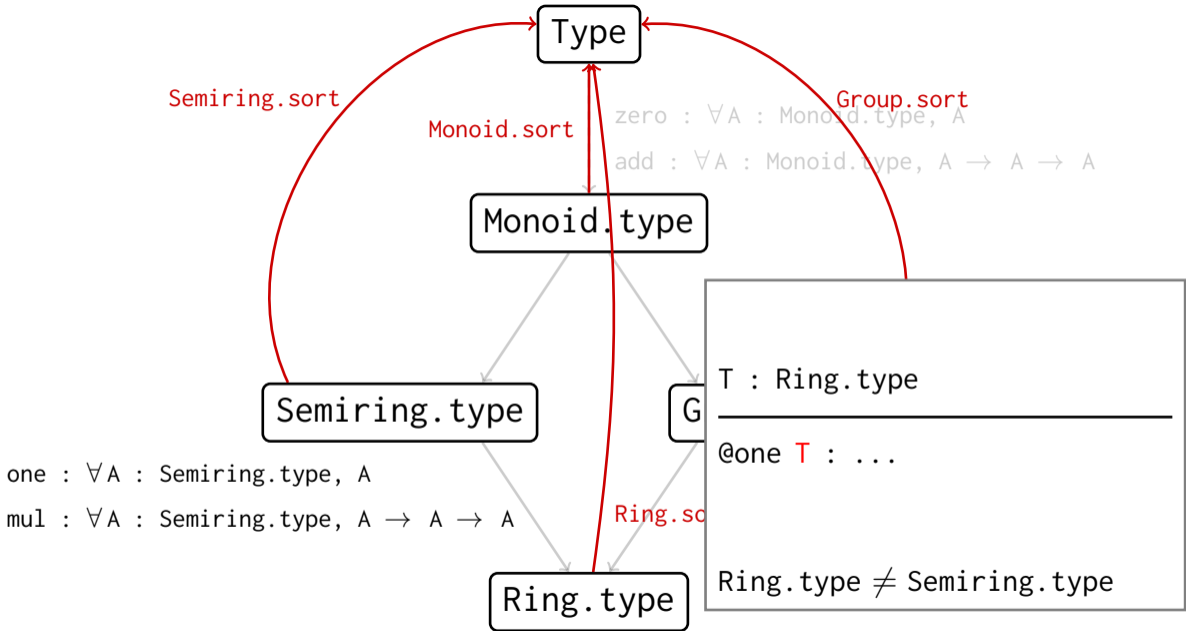
add :  $\forall A : \text{Monoid.type}, A \rightarrow A \rightarrow A$

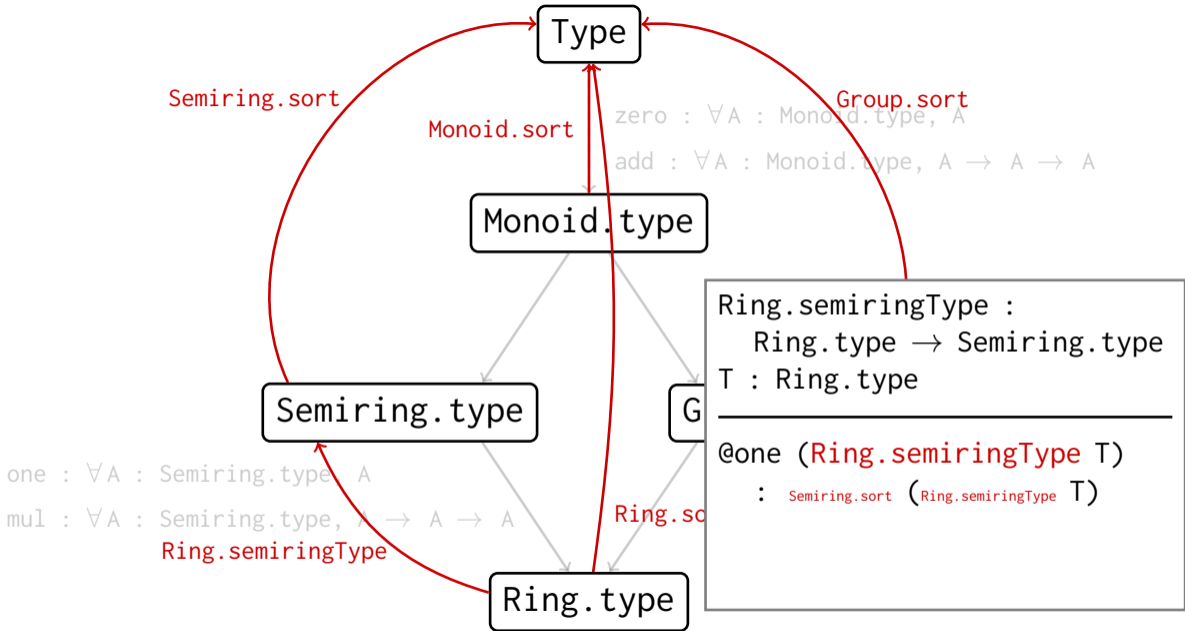
zero :  $\forall A : \text{Monoid.type}, A$

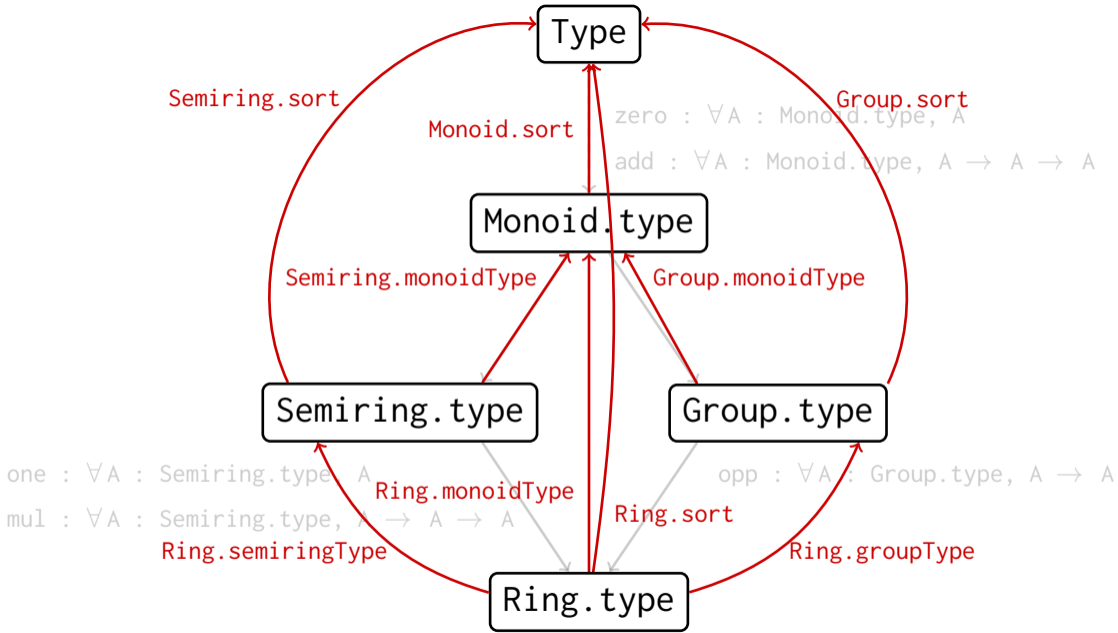












# Implicit coercions

- ▶ If a structure B (transitively) inherits a structure A, we should declare an implicit coercion  $B \rightarrow A$ .
  - ▶ Transitive ones can be automatically computed by Coq, but we declare them explicitly to mitigate performance issues.



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- ▶ There are ambiguous paths for multiple inheritances, e.g.,

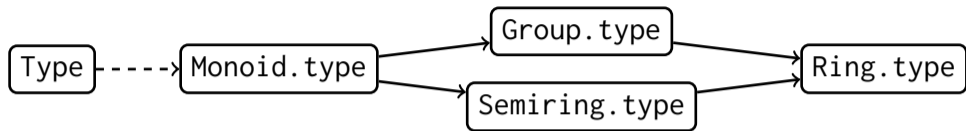
```
[Ring.monoidType] : Ring.type -> Monoid.type.  
[Ring.groupType; Group.monoidType] : Ring.type -> Monoid.type.  
[Ring.semiringType; Semiring.monoidType] : Ring.type -> Monoid.type.
```

- ▶ If we use packed classes correctly, these ambiguous paths will be convertible with each other. If they aren't, the hierarchy is broken.

# Implicit coercions

- ▶ We had no systematic way to detect inconvertible ambiguous paths in Coq 8.9, because it reports all inheritance paths as ambiguous that have the same classes as existing ones.
- ▶ We have relaxed the condition of ambiguous paths by convertibility checking. Coq 8.10 will report only inconvertible ones as ambiguous: `coq/coq#9743`.
  - ▶ This ambiguity checking is nontrivial in general, but we found that it's easy for **uniform inheritances**.

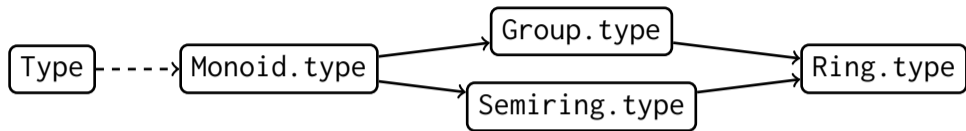
# Automated structure inference



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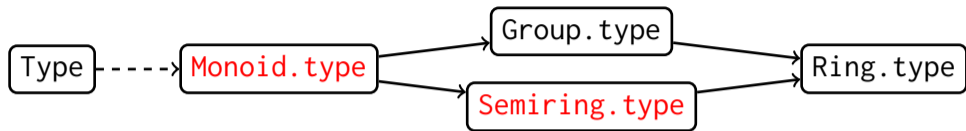
$\vdash @add ?_1 (@zero ?_1) (@one ?_2) : \dots$

# Automated structure inference



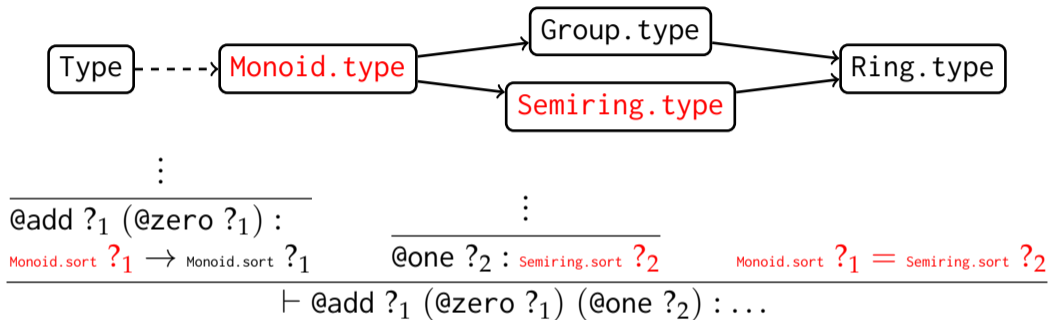
$$\frac{\begin{array}{c} \vdots \\ \hline @add ?_1 (@zero ?_1) : \\ \text{Monoid.sort } ?_1 \rightarrow \text{Monoid.sort } ?_1 \end{array}}{\frac{\begin{array}{c} \vdots \\ \hline @one ?_2 : \text{Semiring.sort } ?_2 \end{array}}{\vdash @add ?_1 (@zero ?_1) (@one ?_2) : \dots}}$$

# Automated structure inference



$$\frac{\begin{array}{c} \vdots \\ \hline @add ?_1 (@zero ?_1) : \\ \text{Monoid.sort } ?_1 \rightarrow \text{Monoid.sort } ?_1 \end{array}}{\frac{\begin{array}{c} \vdots \\ \hline @one ?_2 : \text{Semiring.sort } ?_2 \end{array} \quad \text{Monoid.sort } ?_1 = \text{Semiring.sort } ?_2}{\vdash @add ?_1 (@zero ?_1) (@one ?_2) : \dots}}$$

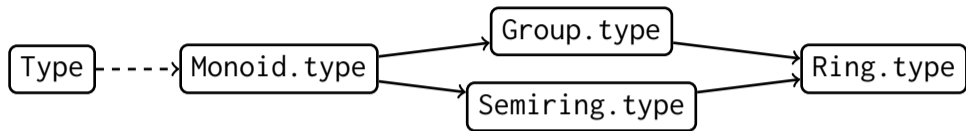
# Automated structure inference



The canonical solution is:

$$?_1 := \text{Semiring.monoidType } ?_2.$$

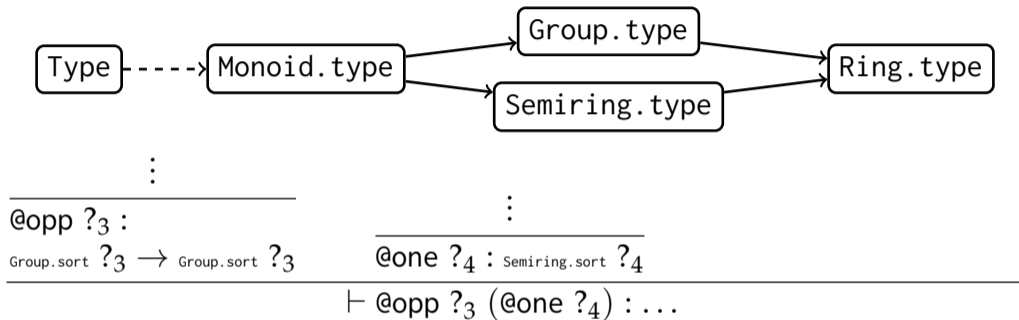
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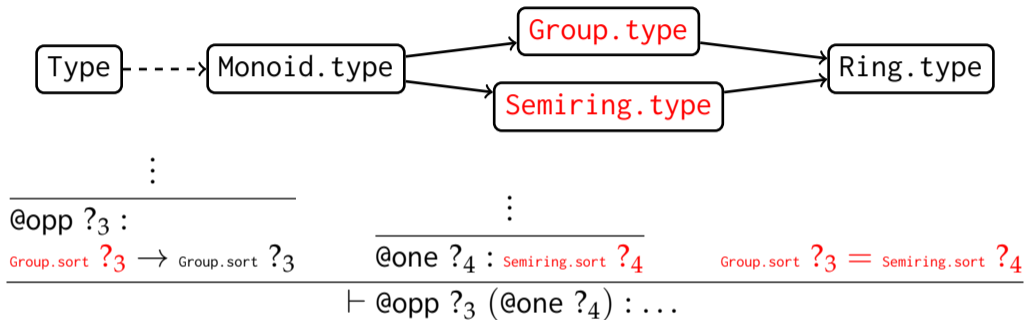
$\vdash @\text{opp } ?_3 (@\text{one } ?_4) : \dots$

# Automated structure inference

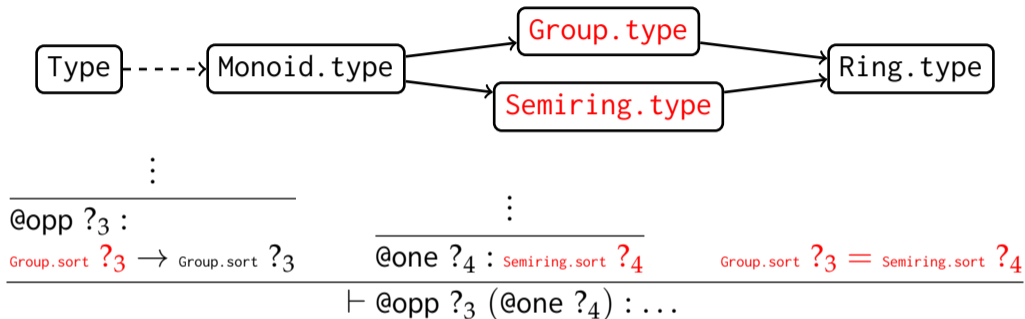




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The canonical solution is:

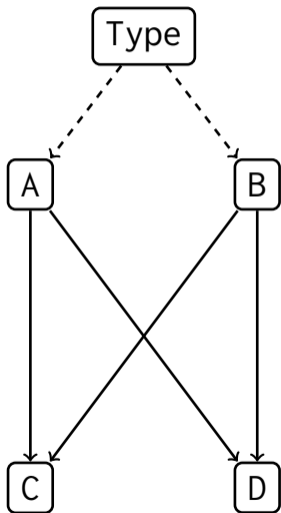
```

fresh ?5 : Ring.type,
  ?3 := Ring.groupType ?5,
  ?4 := Ring.semiringType ?5.
  
```

# Automated structure inference

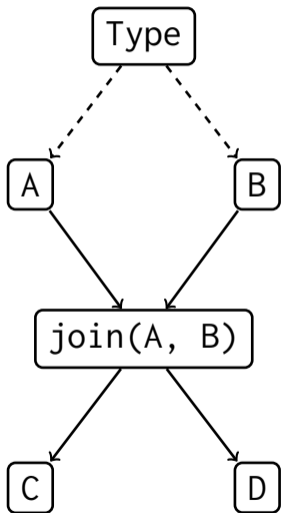
- ▶ To solve a unification problem  $A.sort \_ = B.sort \_$ , we need to find the **join** structure  $C$  of  $A$  and  $B$ .
  - ▶  $C$  must be a maximal common subclass of  $A$  and  $B$ .
  - ▶  $C$  is  $A$  if  $A$  inherits  $B$ , and is  $B$  if  $B$  inherits  $A$ .
  - ▶  $C$  is undefined if  $A$  and  $B$  have no common subclass.
- ▶ For any two structures, their **join must be unique**.
  - ▶ For a given inheritance diagram, we can validate this property and generate a set of assertions which state that “ $C$  is the join of  $A$  and  $B$ ”.
  - ▶ Generated assertions can be checked by Ltac script.

# Why joins must be unique?



- ▶ The structures A and B have two maximal common subclasses C and D which inherit both A and B and have extra axioms.
- ▶ Which structure should be inferred from  $A.sort \_ = B.sort \_$ ?
  - ▶ If C is inferred as their join, it can never be D, and vice versa.

# Why joins must be unique?



- ▶ The structures A and B have two maximal common subclasses C and D which inherit both A and B and have extra axioms.
- ▶ Which structure should be inferred from `A.sort _ = B.sort _`?
  - ▶ If C is inferred as their join, it can never be D, and vice versa.
- ▶ We must disambiguate it by declaring an intermediate structure that just inherits both A and B without no extra axioms.

# Assertions

```
check_join Group.type Group.type Group.type.  
check_join Group.type Monoid.type Group.type.  
check_join Group.type Ring.type Ring.type.  
check_join Group.type Semiring.type Ring.type.  
check_join Monoid.type Group.type Group.type.  
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...
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- ▶ Line 4 asserts that “the join of groups and semirings are rings.”

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...
```

- ▶ Line 4 asserts that “the join of groups and semirings are rings.”
- ▶ Lines 2 and 5 are symmetric ones.  
We need both of them because unification is asymmetric in Coq!



# Generating exhaustive assertions for join

**Function**  $\text{join}(t_1, t_2)$ :

$T := (\{t \mid t_1 \rightarrow^* t\}) \cap (\{t \mid t_2 \rightarrow^* t\});$

*/\* T is the set of all the common subclasses of  $t_1$  and  $t_2$ . \*/*

**foreach**  $t \in T$  **do**  $T \leftarrow \{t' \in T \mid \neg t \rightarrow^+ t'\};$

**if**  $T = \emptyset$  **then return** None; */\* There is no join of  $t_1$  and  $t_2$ . \*/*

**else if**  $T$  is singleton  $\{t\}$  **then return** Some  $t$ ; */\*  $t$  is the join of  $t_1$  and  $t_2$ . \*/*

**else fail**; */\* A join must not be ambiguous. \*/*

**foreach**  $t_1 \in H, t_2 \in H$  **do**

**if**  $\text{join}(t_1, t_2)$  is (Some  $t_3$ ) **then print** (check\_join  $t_1$   $t_2$   $t_3$ );

**end**

---

$\rightarrow^*$  and  $\rightarrow^+$  are the reflexive transitive and transitive closures of the inheritance relation respectively.

# Hunting inheritance bugs with our tool

- ▶ We found and fixed many inheritance bugs in MathComp.
  - ▶ `finalg` structures didn't inherit `countalg` structures. It made many joins ambiguous.
  - ▶ The `finType` instance of `extremal_group` wrongly overwrites the join of `finType` and `countType`.

# Future work

- ▶ Automating structure/inheritance declarations by meta-programming in coq-elpi (with Enrico Tassi and Cyril Cohen).

# References I



François Garillot, Georges Gonthier, Assia Mahboubi, and Laurence Rideau. “Packaging Mathematical Structures”. In: *TPHOLs '09*. Vol. 5674. LNCS. Springer, 2009, pp. 327–342.



Assia Mahboubi and Enrico Tassi. “Canonical Structures for the Working Coq User”. In: *ITP '13*. Vol. 7998. LNCS. Springer, 2013, pp. 19–34.

# Uniform inheritance condition

For classes  $C$  and  $D$  with  $n$  and  $m$  parameters respectively, a coercion  $f : C \rightsquigarrow D$  is a **uniform inheritance** iff

$$f : \forall (x_1 : A_1) \dots (x_n : A_n) (y : C \ x_1 \dots x_n), D \ u_1 \dots u_m.$$

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