

CALL FOR PAPERS
Third International Workshop on
Synthetic Simulation and Robotics to Mitigate Earthquake Disaster
(SRMED 2006)
June 16th , 2006 (tentative)
Messe Bremen, Bremen, Germany

OBJECTIVE

The goal of the Workshop is to provide a forum for discussion and exchange of ideas among researchers aiming at the design and implementation of simulation and robotic systems to support search and rescue operations after catastrophic events in urban environments, in particular in post-earthquake scenarios.

TOPICS

Topics of interest include (but are not limited to):

- Integration of robotic agents in the simulator
- Test field and metric for rescue robotics
- Evaluation methodology for rescue systems
- Future development of competitions and standards
- Rescue simulator extensions
- Rescue robots design
- Autonomy in rescue robots
- Experiences with rescue projects

PAPER SUBMISSION

Please send a PDF file of a full paper within 6 pages (for a long paper), or an abstract with 1 page (for a short paper) by e-mail to

Itsuki Noda (srmed2006@m.aist.go.jp)

The deadline is May 30, 2006

PROGRAM (tentative)

June 16th	10:00 am	Display posters in the competition field area specified on site
	13:00 pm	Question and Answer Session for posters
		Panel Discussion on technical issue concerning rescue systems

POSTER PRESENTATION

All papers are presented by posters. Accepted authors should make 2 copies of posters, and display one poster in the competition field area. The other poster is used for panel discussions.

SCHEDULE

May 30, 2006	Deadline of paper submission (full paper or short paper)
June 1, 2006	Notification of acceptance
June 16, 2006	Workshop (poster and panel), Deadline of final paper

ORGANIZERS

Itsuki Noda (AIST), Daniele Nardi (U. Roma), Satoshi Tadokoro (Tohoku U.), Tomoichi Takahashi (Meijo U.), Adam Jacoff (NIST), Luca Iocchi (U. Roma), Ikuo Takeuchi (U. Tokyo)